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# Decision-Based Metrics for Test and Evaluation Experiments

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# Decision-Based Metrics for Test and Evaluation Experiments

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# Research Question

- Sequential sampling rules can be used to decide the number of experimental replications
- These rules are often made independently of the desired outcome or decision.
- Let  $D$  be the decision threshold for making a decision about a system.

How can we use decision criteria to inform sequential sampling rules?

# Confidence Intervals

$$\left[ \bar{x}_n \pm t_{\alpha, n-1} \frac{s_n}{\sqrt{n}} \right]$$

Estimated mean

Estimated standard deviation

Half-width

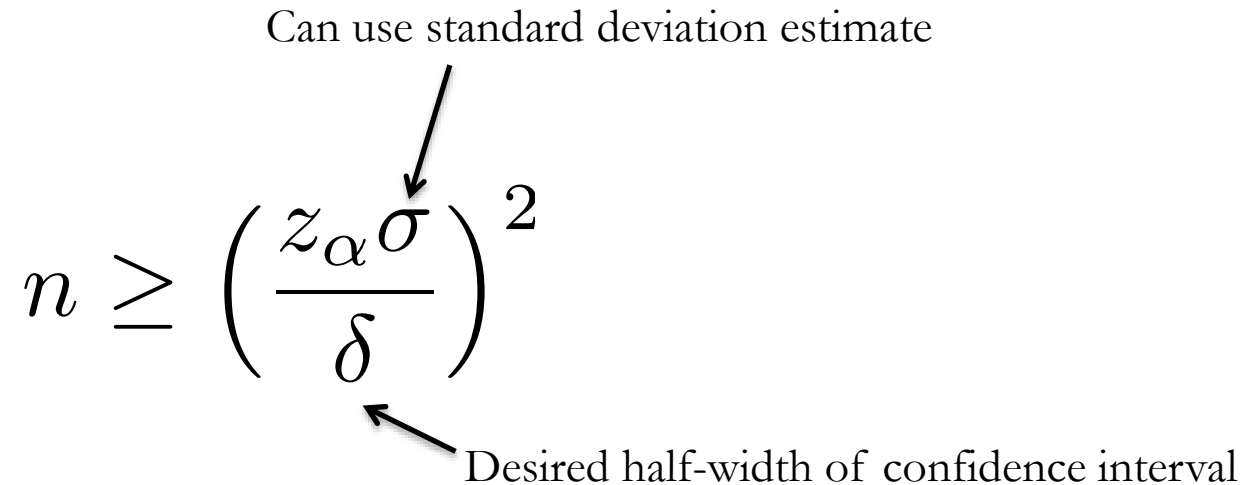
- Confidence intervals represent the uncertainty in the mean performance of a system based on  $n$  samples
- Often assume normality in the data
- The half-width should be small enough to ensure that the variation in the mean estimate is acceptable

# Fixed Sampling Rules – Choosing the sample size

Can use standard deviation estimate

$$n \geq \left( \frac{z_{\alpha} \sigma}{\delta} \right)^2$$

Desired half-width of confidence interval

The diagram shows the formula for sample size n. An arrow points from the text 'Can use standard deviation estimate' to the sigma symbol in the numerator of the fraction. Another arrow points from the text 'Desired half-width of confidence interval' to the delta symbol in the denominator of the fraction.

- If a variance estimate is available, can calculate ahead of time how many samples should be taken to obtain a confidence interval with a half-width smaller than  $\delta$ .
- Challenges:
  - hard to choose  $\delta$
  - $n$  might be large
  - Variance estimate might not be available

# Solution: Sequential Sampling Rules

**Absolute precision** rules: fix a value of  $\delta$  and collect samples until the half-width is smaller than  $\delta$ .

$$n^* = \text{smallest } n \text{ s.t. } t_{\alpha, n-1} \frac{s_n}{\sqrt{n}} \leq \delta$$

**Relative precision** rules: fix a percentage  $\delta$  and collect samples until the half-width is within some percent of the sample mean.

$$n^* = \text{smallest } n \text{ s.t. } t_{\alpha, n-1} \frac{s_n}{\sqrt{n}} \leq \delta \bar{x}_n$$

Pros: can stop earlier when desired precision is reached, do not need variance estimate ahead of time

Cons: statistical bias (confidence interval coverage  $< 1 - \alpha$ ), could still require a large number of samples

# Example from Small Arms Testing

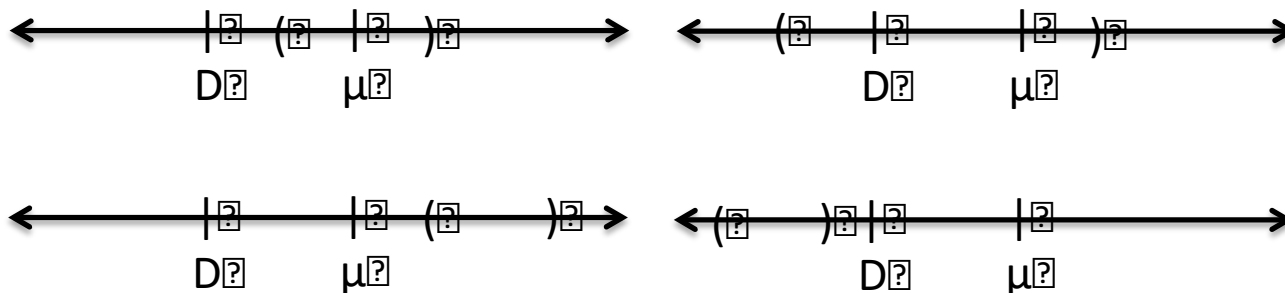
Table reproduced from TOP 3-2-045

<u>ITEM</u>	<u>MAXIMUM PERMISSIBLE ERROR OF MEASUREMENT*</u>
Brookfield viscometer	$\pm 0.5\%$ full-scale reading.
Cyclic rate recorder	$\pm 1\%$ at rates up to 6000 spm and burst lengths of 100 rounds.
Stargage and airgage	$\pm 0.025$ mm.
Thermograph/thermocouples	$\pm 0.6$ °C (1 °F).
Velocimeter	0.1% or 0.5 m/s (whichever is highest) for bursts to 6000 spm.

\*Values can be assumed to represent  $\pm 2$  standard deviations.

# Four Types of Confidence Interval (CI) Results

- Let  $\mu$  be the true mean system performance.
- Let  $D$  be the decision threshold
  - If  $CI > D$ , then “Accept” the system as meeting the requirement
  - If  $CI < D$ , or includes  $D$ , then “Reject” the system as failing to meet the requirement
- Confidence intervals can either
  - correctly include (cover)  $\mu$  or not
  - correctly determine whether  $\mu$  is greater than  $D$ , or not.



Cover & Correct	Cover & Incorrect
Fail to cover & Correct	Fail to cover & Incorrect



# Decision-Based Procedures

- Traditional sequential rules do not incorporate  $D$
- New rules directly incorporate  $D$  in the stopping criterion

$$n^* = \text{smallest } n \text{ s.t. } t_{\alpha, n-1} \frac{s_n}{\sqrt{n}} \leq |\bar{x}_n - D|$$

- Results in confidence intervals that usually do not include  $D$
- Will require more samples if the true performance is close to  $D$ 
  - Ensures precise confidence interval if decision is a close call
- Will end early if true performance is far from  $D$ 
  - Saves time/replications if the decision is obvious

# Conclusions and Implementation

- The expected number of samples required by the procedure depends on how far the unknown  $\mu$  is from the known requirement  $D$ .
- $\sigma=1, 1-\alpha=90\%$

$ \mu - D $	Expected no. samples
1.0	5.0
0.5	10.9
0.3	28.6
0.1	263.9
0.05	1095.9
0.0	$\infty$

Confidence interval coverage can be poor for small sample sizes.  
Solution: aim for high confidence (99%) known actual confidence may be closer to 95% or 90%.

# Conclusions and Future Work

- Developed a new sequential stopping rule that incorporates the decision requirement  $D$ .
  - Potentially more efficient in making a decision.
- There may be significant bias associated with sequential rules, along with our proposed modifications. Simulation testing can be used to estimate the bias.
- Looking for ongoing/real test data to estimate the impact of sequential rules.