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Solid State Circuit Breaker with Reduced Clamping Voltage

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(54) **SOLID STATE CIRCUIT BREAKER WITH REDUCED CLAMPING VOLTAGE**

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H02H 9/04 (2006.01)
H01C 7/108 (2006.01)
H01C 7/12 (2006.01)
H01H 9/54 (2006.01)

(52) **U.S. Cl.**
CPC **H02H 9/04** (2013.01); **H01C 7/108** (2013.01); **H01C 7/12** (2013.01); **H01H 2009/543** (2013.01)

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CPC H02H 9/04; H02H 3/087; H02H 9/043; H02H 7/205; H01C 7/108; H01C 7/12; H01C 7/112; H01H 2009/543
USPC 361/2-13
See application file for complete search history.

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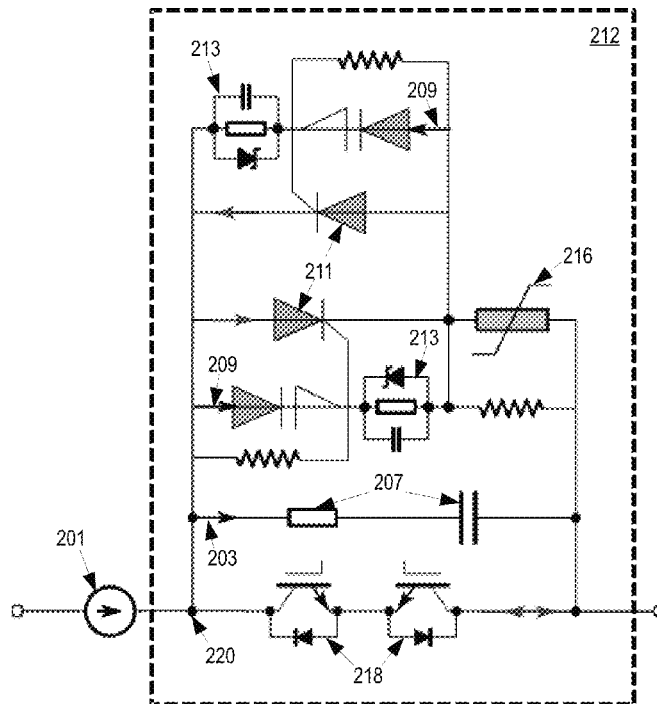
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(57) **ABSTRACT**

A solid state circuit breaker that may include a metal oxide varistor (MOV) that is connected in series to a thyristor, the MOV to clamp voltage of current flowing through the solid state circuit breaker; the thyristor including a gate to control flow of the current to the MOV along a first path to the MOV; a breakover diode to activate at a target voltage level to allow the current to flow to the MOV along a second path; and a Zener diode to close the gate and allow current to flow along the first path in response to the current on the second path.

16 Claims, 2 Drawing Sheets



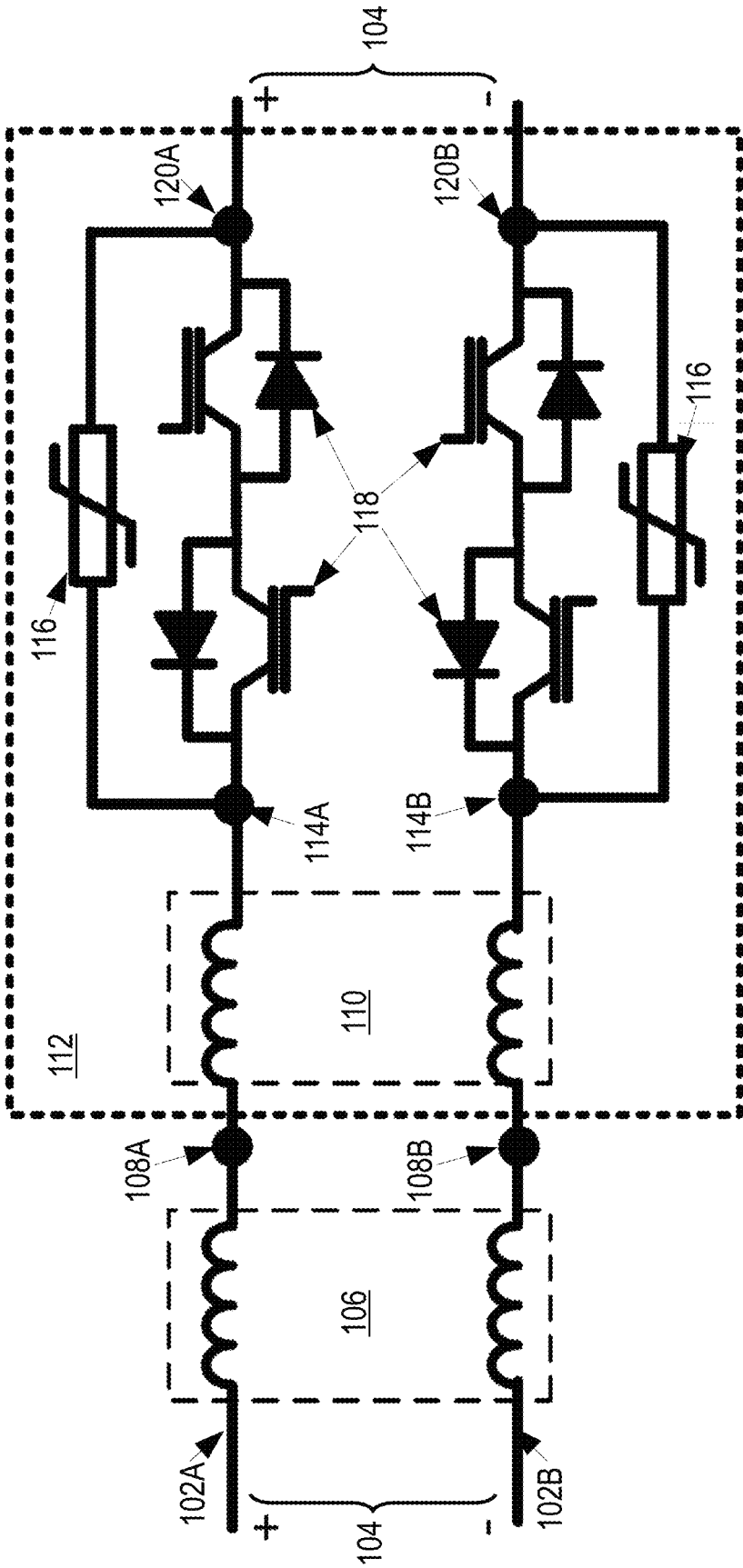


FIG. 1
(Prior Art)

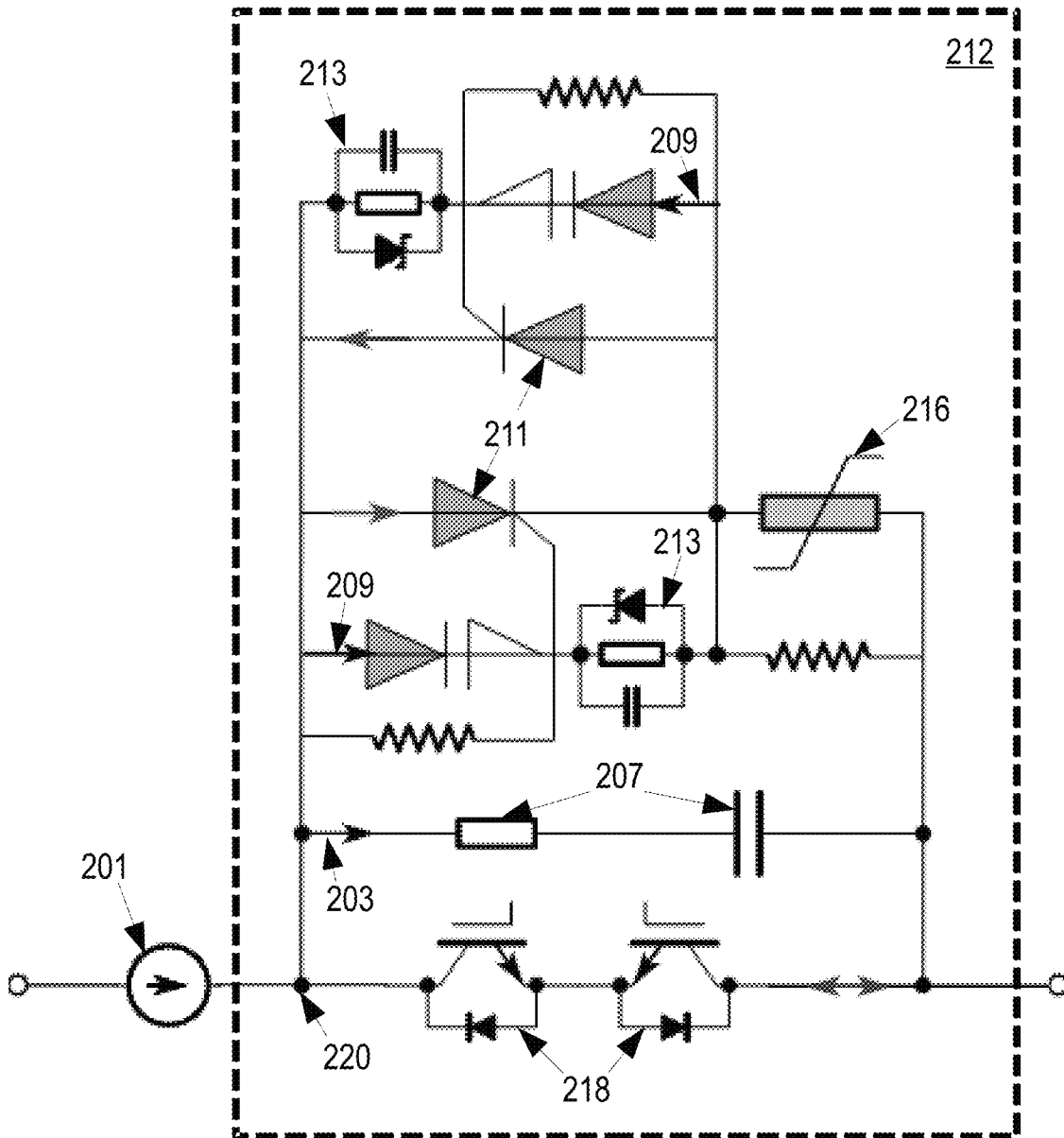


FIG. 2

SOLID STATE CIRCUIT BREAKER WITH REDUCED CLAMPING VOLTAGE

CROSS-REFERENCE TO RELATED APPLICATIONS

This patent application is a non-provisional of and claims the benefit of U.S. Provisional application 63/173,329, filed Apr. 9, 2021, which is hereby incorporated by reference in its entirety.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present disclosure relates to solid state circuit breakers (SSCB's) in general, and, more particularly, to SSCB's suitable for protecting hybrid electric propulsion systems.

2. Description of the Related Art

Hybrid electric propulsion can improve fuel burn efficiency and reduce carbon emission in aviation applications. The power rating of the electrical power system to support hybrid electric propulsion is in the range of megawatts (MWs) or tens of MWs, which is much higher than the existing power system on existing commercial aircrafts. To reduce the total weight of electric power system, especially the cable weight, a medium voltage direct current (MVDC) system is selected due to its numerous advantages compared with the traditional alternative current (ac) system. However, the circuit breaker can create difficulties in the MVDC concept because the system fault current does not cross zero naturally like in an ac system. In addition, due to the lack of impedance to limit the fault current rising speed, the circuit breaker also should respond ultra-fast to avoid severe damage caused by the potential high fault current.

An SSCB can protect the hybrid electric propulsion system because of its rapid response time and simplicity compared to other alternatives, such as the mechanical circuit breaker and hybrid circuit breaker. An SSCB mainly consists of a semiconductor switch, an energy absorber, and a fault current limiting device.

SUMMARY OF THE INVENTION

Embodiments described herein related to a solid state circuit breaker. In some cases, the solid state circuit breaker includes a metal oxide varistor (MOV) that is connected in series to a thyristor, the MOV to clamp voltage of current flowing through the solid state circuit breaker; the thyristor comprising a gate to control flow of the current to the MOV along a first path to the MOV; a breakover diode to activate at a target voltage level to allow the current to flow to the MOV along a second path; and a Zener diode to close the gate and allow current to flow along the first path in response to the current on the second path.

In some embodiments, the solid state circuit breaker further includes a second thyristor that is antiparallel to the thyristor and is connected in series to the MOV, the second thyristor comprising a second gate to control flow of the current to the MOV along a third path.

Embodiments in accordance with the invention are best understood by reference to the following detailed description when read in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 shows a typical SSCB in accordance with the prior art.

FIG. 2 shows a SSCB in accordance with the prior with embodiments.

Embodiments in accordance with the invention are further described herein with reference to the drawings.

DETAILED DESCRIPTION OF THE INVENTION

The following description is provided to enable any person skilled in the art to use the invention and sets forth the best mode contemplated by the inventor for carrying out the invention. Various modifications, however, will remain readily apparent to those skilled in the art since the principles of the present invention are defined herein specifically to provide to solid state circuit breakers.

A typical SSCB **112** in the prior art is shown in FIG. 1. In normal operation, the power semiconductors **118** are turned on to carry current. When the system current surges due to system fault, such as ground or line to line short circuit fault, the power semiconductors **118** are turned off commutating system fault current to their parallel the metal oxide varistors (MOVs) **116**. Then, the MOV can reduce the fault current and finally clear the faults.

In some examples, the power semiconductors **118** may be insulated-gate bipolar transistors (IGBT). Other SSCB **112** involving different types of semiconductors, such as Silicon carbide metal-oxide-semiconductor field-effect transistors can be used. Under normal operation condition, the voltage across the SSCB **112** is close to zero and system current only flows through the power semiconductors **118**. When a short circuit fault occurs, and the power semiconductors' **118** current increases. The rising slope of power semiconductors' **118** current is determined by the system dc voltage **104**, the total inductance of the system (L_{sys}) **106**, and inductance of the SSCB (L_{CB}) **110**. It is noteworthy that L_{sys} **106** is not only determined by the system parameters, such as cable length, but also the fault location.

For example, if the B **108A** and B' **108B** are shorted, the short circuit current flowing through the SSCB **112** in FIG. 1 is limited by the L_{CB} **110** no matter the value of the system inductance **106**. This is a reason to consider the fault current limiting inductor in the traditional design to ensure that the peak fault current is within the safe level even in the extreme case.

When the fault current exceeds the predefined protection level, the fault protection scheme is activated. After a certain delay time, the power semiconductors **118** are turned off and commutate the current to MOV **116**. In between, the peak fault current could be clamped by the power semiconductors **118** saturation current level. Those skilled in the art will appreciate that power semiconductors **118** such as IGBT's normally operates in saturation region with only a few volts voltage drop. Once the current is high enough, an IGBT **118** exits the saturation region and enters the active region, and the voltage across the IGBT **118** increases rapidly until it reaches the system dc voltage level **104**. After the system dc voltage level **104** is reached, the system current or IGBT **118** current cannot further increase and is clamped instead.

When the power semiconductors **118** are turned off, the current flowing through power semiconductors **118** is commutated into MOV **116** and the voltage across the SSCB is determined by the MOV **116** clamping voltage, which is higher than the system dc voltage **104** and eventually drive

the system current to zero and clear the fault. After that, MOV **116** continues to block the system dc voltage **104**.

To support the operation of SSCB **112**, the MOV **116** should be able to block the system dc voltage **104** continuously, which means the leakage current of MOV **116** at system dc voltage **104** should be low enough not to cause thermal stress. Secondly, the MOV's **116** clamping voltage when carry the system fault current should be lower than the power semiconductors' **118** voltage rating; otherwise, the power semiconductors **118** can be damaged by over voltage in as short as a few μ s.

Those skilled in the art will appreciate that semiconductors **118** with higher voltage rating generate more conduction loss when carrying the same current. Thus, to minimize the SSCB **112** power loss, which is dominated by the semiconductors' **118** conduction loss, a semiconductor **118** with lower voltage rating is preferred. In other words, a MOV **116** that can block the system voltage **104** continuously and have lower clamping voltage can help to improve the SSCB **112** efficiency. A typical ratio between the MOV **116** clamping voltage and continuous blocking voltage is around 2.

Embodiments described herein reduce peak clamp voltage in comparison to the classic topology in FIG. 1. In some embodiments, two antiparallel thyristors are connected in series with a MOV. During normal operation, the thyristors are off and power semiconductors carry the load current. The thyristors can be activated after the fault is detected and before the power semiconductors are turned on. Before the power semiconductors are turned on, a thyristor withstands the voltage across the SSCB. After the power semiconductors are turned on, the SSCB's voltage will be applied to MOV. Then the power semiconductors can be turned off and the fault current can flow through the MOV, similar to the classical SSCB. When the fault current flows through the MOV, the thyristor's gate voltage can be removed. Since the thyristor cannot be forced to turn off, the thyristor maintains an on state until the fault current is reduced by MOV to a level which is lower than the hold on current level of the thyristor. Then the thyristors and MOV can withstand the dc system voltage together; however, the leakage current of the thyristors is much lower than the leakage current of MOV. In other words, the equivalent resistance of the thyristors is much higher than the MOV, so most of the voltage is withstood by the thyristors. In these embodiments, the power loss in the MOV is negligible. It was previously assumed that the MOV current could only flow through the thyristors, which is true if the thyristors have active controlled gate drive. If additional passive control circuit are involved to boost the system simplicity and reliability, the thyristor only shares part of the system voltage while still reducing the peak clamp voltage.

In prior art systems, several MOVs can be used in parallel to shape the equivalent MOV V/I curve to reduce the peak clamping voltage (fault current is shared by the parallel MOVs thus reducing the current per MOV and hence its voltage). However, parallel MOVs increases the weight, size and cost of the SSCB. Embodiments herein describe a new voltage clamping circuit (VCC), coined as the electronic MOV or eMOV module, to address the aforementioned drawbacks.

A SSCB **212** exemplifying the proposed embodiment is shown in FIG. 2. The SSCB **212** includes RC slapper **207**, breakover diodes **209**, thyristors **211**, Zener diodes **213**, MOVs **216**, and power semiconductors **218**. In the proposed circuit, additional passive components are added to the traditional MOV **216** circuit which allows the user to

decouple the peak clamping voltage of the VCC from its dc withstand voltage to allow freedom in the selection of the voltage ratio to maximize the voltage utilization of the solid state switch **220**. The main additional components include break over diodes (BOD) **209**, a reverse blocking Zener diode **213**, thyristors (silicon controlled rectifier [SCR]) **211** and RC snubbers (RC slappers) **207** for both the solid state switch **220** and the SCR **211** gate-cathode connections.

With the proposed circuit, the system dc voltage in the standby mode is shared by the BOD **209** and the MOV **216** whereas during the fault transient, the SCR **211** is triggered on (once the BOD **209** breaks over) to allow MOV **216** clamping action much like the traditional circuit. In this way, the MOV **216** peak clamping voltage (and its dc withstand voltage $V_{M,DC}$) value can be selected independent of the system dc voltage to achieve voltage ratios lower than 1.9.

Standby Mode

The voltage/pole is shared by the BOD **209** and the MOV **216** during the standby mode. The BOD **209** is an asymmetrical device (uses a series P-N diode for reverse voltage blocking), which remains reverse biased until the voltage across its Anode-Cathode reaches the breakover voltage V_{BO} . Both the BOD **209** and MOV **216** are non-linear parts with different leakage currents in the nA- μ A range in the blocking region. High value (M1) static balancing resistors can be used in parallel across them to force voltage sharing in the standby mode so that neither of the two ratings, $V_{M,DC}$ or V_{BO} , are exceeded. For successful operation in the standby mode—it should be ensured that the SCR **211** remains in the off state when the total dc voltage V_{dc} is applied across the pole (single pole interruption case). The MOV **216** and BOD **209** parts are selected such that (1) is met:

$$V_{M,DC} + V_{BO} > V_{dc} \quad (1)$$

Another important point to note is that the total leakage current of the eMOV **209**, **211**, **216** in the standby mode should be below the SCR holding current so it will be turned off during this period.

Fault Turn-Off Transient

During the fault turn-off event, the eMOV circuit **209**, **211**, **216** should trigger the SCR **211** "on" to allow transfer of the fault current to the MOV **216**. The current continues to flow through the solid state switch **220** until it is gated off. After the solid state switch **220** is gated off, the current transfers to the RC branch **203** charging the snubber **207** capacitor. Those skilled in the art will appreciate that the snubber **207** is optional. The BOD **209** being a much smaller part (in comparison to the MOV **216**) has a lower leakage current (in nA), and the BOD's **209** voltage starts to increase during this time period. Once the BOD **209** voltage reaches V_{BO} , the BOD **209** starts to conduct, immediately triggering on the SCR **211** to commutate the current to the MOV **216**. The total voltage across the solid state switch **220** at this point is given by V_{th} which is the sum of the breakover voltage V_{BO} of the BOD **209** and the MOV **216** voltage at the breakover current, i.e. $V_{MOV}(I_{BO})$, (typically ~ 15 mA).

After the BOD **209** voltage reaches V_{BO} , the MOV **216** establishes the clamping voltage and drives the fault current to zero. The RC snubber **207** branch in parallel with the solid state device **218** helps ensure that the SCR **211** di/dt and dv/dt are below its critical limits. To prevent overvoltage across the solid state switch **220** (i.e. the voltage rating

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$V_{SS,rated}$ is not exceeded), the following two conditions should be satisfied:

$$V_{MOV(I_{BO})} + V_{BO} < V_{SS,rated} \quad (2)$$

$$V_{MOV(I_{pk})} < V_{SS,rated} \quad (3)$$

In some embodiments described herein, the MOV **216** can be selected based on the requirement of maximum clamp voltage, which is determined by the power semiconductors **218** voltage rating. This allows power semiconductors **218** with a low voltage rating to be selected, which substantially increases the efficiency of SSCB **212**. For example, if the system dc voltage is 1 kV, a 3.3 kV class IGBT **218** can be selected instead of a 4.5 kV class IGBT **218** in the prior art method. Further, any MOV **216** with a clamping voltage lower than 3.3 kV can be used as long as the MOV's **216** leakage current at system dc voltage is lower than hold on current level of the thyristor **211**. In this example, the V112BB60 MOV **211** can be used since the leakage current when MOV **216** is blocking 1.8 kV dc voltage is in the range of 100 s of mA, which is low enough to allow the thyristor **211** self-turn-off.

In some embodiments described herein, thyristors **211** are not carrying current during normal operation, so no additional power loss is introduced with the added thyristors **211**. Thus, there is no power loss penalty, which improves SSCB **212** efficiency.

For example, if 4.5 kV device is selected as the thyristors **211**, such as FZ800R45KL3_B5, the voltage drop while carrying 1000 A is 3.5V. If 3.3 kV device is selected as the thyristors **211**, such as FZ1400R33HE4, which has the same physical dimension as FZ800R45KL3_B5, the voltage drop while carrying the same current is 2.5V. In other words, the power loss can be reduced by 30%.

In some embodiments, the thyristors **211** should handle the same fault current flowing through MOV **216**; however, thyristors **211** have a much better surge current handling capability compared with other semiconductor devices. For example, a 320 A 3.3 kV thyristor **211** can handle 5 kA for 10 ms, and with passive control circuit, the thyristor **211** voltage rating can be further reduced such that, for example, a 1600V 181 A thyristor **211** can handle 6 kA for 10 ms. Considering fault current is typically cleared within 10 s to 100 s of μ s, a thyristor **211** with a low current rating or mechanical dimension/weight can meet the requirement, which has minimum impact on the system design.

To achieve the above-mentioned benefits, the thyristors **211** should be turned on after a fault is detected and turned off after fault current is reduced by MOV **216** to allow the fault current flowing through MOV **216**.

In some embodiments, the thyristor **211** control can be implemented with an active control gate circuit. With the active control circuit, a separated control signal is used to trigger the gate drive circuit of the thyristor **211**, such as the fault detection signal from the SS switch **220** drive or separate digital controller. Further, power supply and additional gate drive boards can be used to turn on the thyristor **211** when the digital signal is received. This technique provides a lot of control freedom but can also introduce additional components which will increase the SSCB **212** complexity, weight, and may affect the reliability of the devices.

In some embodiments, components of SSCB **212** can be selected according to the following criteria:

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MOV **206** leakage current at system dc voltage should be lower than the thyristor **211** hold-on current level.

MOV **206** clamping voltage must be lower than the semiconductor **218** voltage rating.

If the MOV **206** leakage current is I_0 when it withstands its maximum continuous voltage. The BOD **209** voltage at the leakage current of I_0 should be higher than the difference between the system dc voltage and MOV's **206** maximum continuous voltage.

If the BOD **209** current is I_1 , when it reaches its break over voltage level. The MOV voltage at the current of I_1 should be lower than the difference between the semiconductor **218** voltage rating and the BOD **209** breakover voltage.

This description provides exemplary embodiments of the present invention. The scope of the present invention is not limited by these exemplary embodiments. Numerous variations, whether explicitly provided for by the specification or implied by the specification or not, may be implemented by one of skill in the art in view of this disclosure.

It is to be understood that the above-described arrangements are only illustrative of the application of the principles of the present invention, and it is not intended to be exhaustive or limit the invention to the precise form disclosed. Numerous modifications and alternative arrangements may be devised by those skilled in the art in light of the above teachings without departing from the spirit and scope of the present invention.

What is claimed is:

1. A solid state circuit breaker comprising:

a metal oxide varistor (MOV) that is connected in series to a thyristor, the MOV to clamp voltage of current flowing through the solid state circuit breaker;

the thyristor comprising a gate to control flow of the current to the MOV along a first path to the MOV;

a breakover diode to activate at a target voltage level to allow the current to flow to the MOV along a second path;

a Zener diode to close the gate and allow current to flow along the first path in response to the current on the second path, and

an RC slapper on a fourth path that bypasses the MOV, the RC slapper to initially and temporarily carry current when the solid state circuit breaker is activated.

2. The solid state circuit breaker of claim 1, further comprising a second thyristor that is antiparallel to the thyristor and is connected in series to the MOV, the second thyristor comprising a second gate to control flow of the current to the MOV along a third path.

3. The solid state circuit breaker of claim 1, wherein the Zener diode further comprises a resistor-capacitor to prevent the thyristor gate from closing prematurely.

4. The solid state circuit breaker of claim 1, wherein the MOV has a voltage ratio between clamping voltage and continuous blocking voltage of less than 1.9.

5. The solid state circuit breaker of claim 1, wherein the MOV has a leakage current at system DC voltage that is lower than a hold-on current level of the thyristor.

6. The solid state circuit breaker of claim 1, wherein the MOV has a clamping voltage that is lower than a voltage rating of a semiconductor connected to the solid state circuit breaker.

7. The solid state circuit breaker of claim 1, wherein the MOV has a leakage current at a maximum continuous voltage, and wherein a voltage of the breakover diode at the leakage current is higher than a difference between a system dc voltage and the maximum continuous voltage.

8. The solid state circuit breaker of claim 1, wherein the breakover diode has a breakover current when the breakover

voltage level is reached, and wherein the MOV has a MOV voltage at the breakover current that is lower than a difference between a voltage rating of a semiconductor connected to the solid state circuit breaker and a breakover voltage of the breakover diode.

9. A solid state circuit breaker comprising:

a metal oxide varistor (MOV) that is connected in series to a first thyristor, the MOV to clamp voltage of current flowing through the solid state circuit breaker;

the first thyristor comprising a first gate to control flow of the current to the MOV along a first path to the MOV;

a breakover diode to activate at a target voltage level to allow the current to flow to the MOV along a second path;

a Zener diode to close the first gate and allow current to flow along the first path in response to the current on the second path; and

a second thyristor that is antiparallel to the first thyristor and is connected in series to the MOV, the second thyristor comprising a second gate to control flow of the current to the MOV along a third path.

10. The solid state circuit breaker of claim 9, further comprising an RC slapper on a fourth path that bypasses the MOV, the RC slapper to initially and temporarily carry current when the solid state circuit breaker is activated.

11. The solid state circuit breaker of claim 9, wherein the Zener diode further comprises a resistor-capacitor to prevent the first gate from closing prematurely.

12. The solid state circuit breaker of claim 9, wherein the MOV has a voltage ratio between clamping voltage and continuous blocking voltage of less than 1.9.

13. The solid state circuit breaker of claim 9, wherein the MOV has a leakage current at system DC voltage that is lower than a hold-on current level of the first thyristor.

14. The solid state circuit breaker of claim 9, wherein the MOV has a clamping voltage that is lower than a voltage rating of a semiconductor connected to the solid state circuit breaker.

15. The solid state circuit breaker of claim 9, wherein the MOV has a leakage current at a maximum continuous voltage, and wherein a voltage of the breakover diode at the leakage current is higher than a difference between a system dc voltage and the maximum continuous voltage.

16. The solid state circuit breaker of claim 9, wherein the breakover diode has a breakover current when the breakover voltage level is reached, and wherein the MOV has a MOV voltage at the breakover current that is lower than a difference between a voltage rating of a semiconductor connected to the solid state circuit breaker and a breakover voltage of the breakover diode.

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